

Features

- USB Specification 1.1 Compliant
- Single 5V Operation
- Low Power
- On-Chip Voltage Regulator
- Single Serial Port
 - Supports up to 920 Kbps Serial Data Rate
 - Supports 5, 6, 7, & 8-bit Data Widths
 - Supports 1, 1.5, & 2 Stop Bits
 - Supports Even, Odd, Mark, Space and None parities
- Single Printer Port Interface
- Internal Power-On Reset
- 2KV In-Circuit ESD protection for lower cost of external components
- Available in 48-Pin QFP Package

Applications

- Monitoring Equipment
- High-Speed Modems
- Printer Server
- Serial Networking
- Printer Interface

Application Note

- AN-7715

Evaluation Board

- MCS7715-EVB

General Description

The MCS7715 controller provides bridging between the Universal Serial Bus (USB) port, an enhanced UART, and a Parallel Printer port. This device contains all the necessary logic to communicate with the host computer via the USB bus. It supports Printers with hardware accelerated SPP mode.

The MCS7715 contains a 3.3V regulator, operates in Bus-Powered mode, and has a reduced frequency (6 MHz) crystal oscillator.

This combination of features allows significant cost savings in system design along with straightforward implementation of Serial Port and Parallel Port functionality into PC peripherals using the host's USB port.

Ordering Information

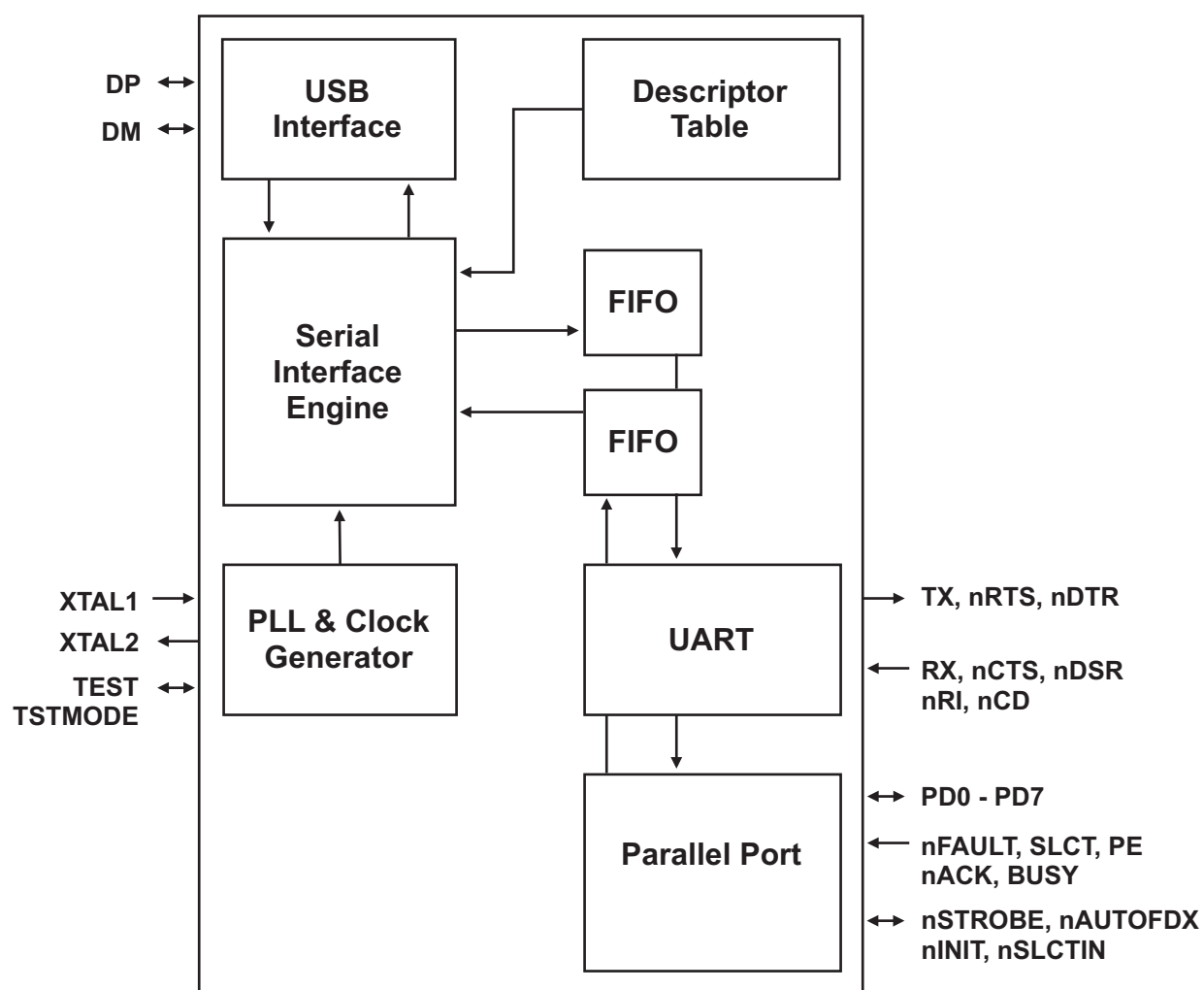
Commercial Grade (0° C to +70° C)		
MCS7715CQ	48-QFP	Standard
MCS7715CQ-GR	48-QFP	RoHS

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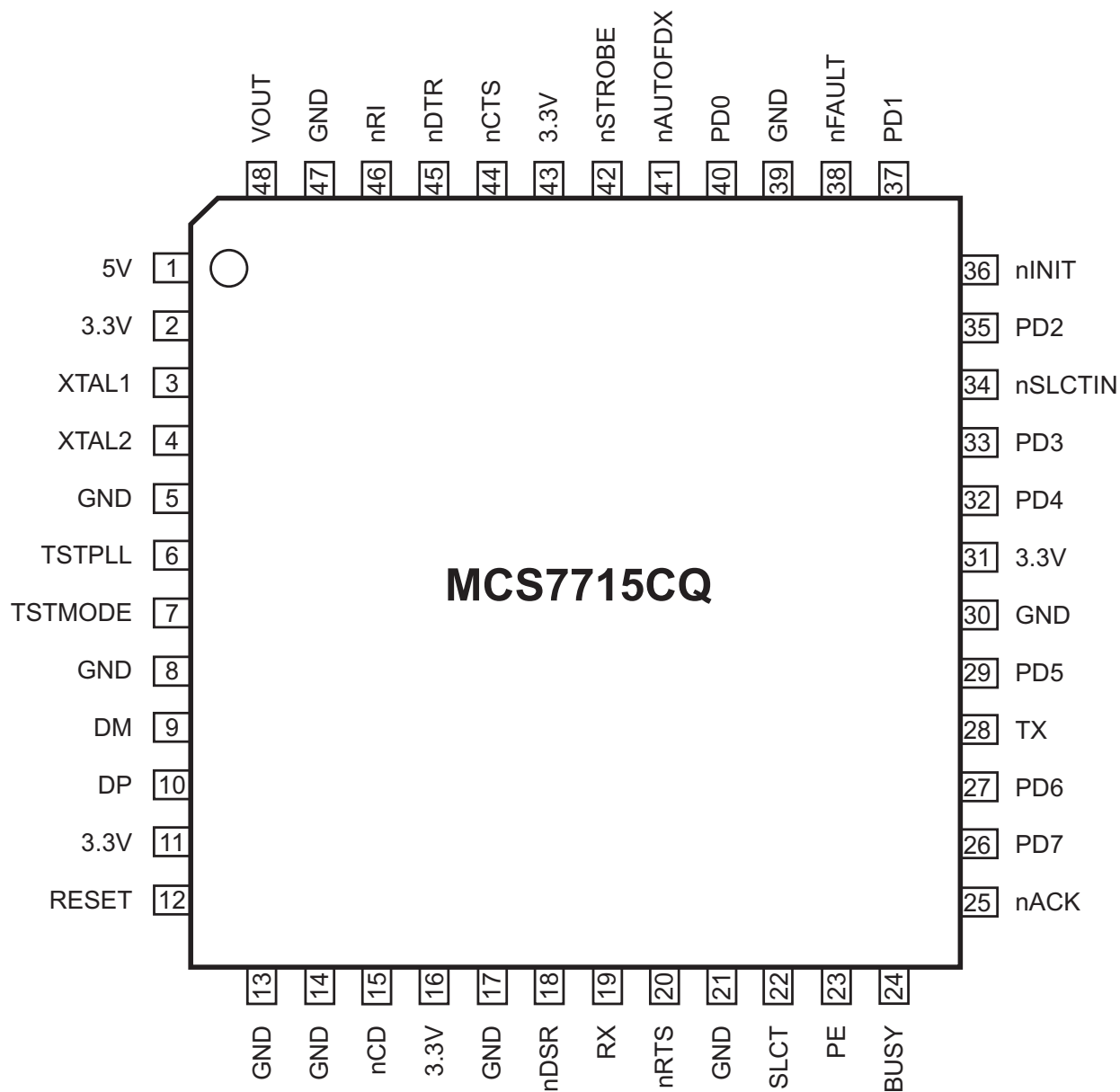
USB 1.1 to Single UART and Printer Port



Block Diagram



Pin-Out



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Pin Assignments

Pin Name	Pin	Type	Description
XTAL1	3	I	Crystal Oscillator input, or External Clock input pin (6 MHz). This signal input is used in conjunction with XTAL2 to form a feedback circuit for the internal timing. Two (10 pF) external capacitors connected from each side of the crystal to GND are required to form a Crystal Oscillator.
XTAL2	4	O	Crystal Oscillator output. See XTAL1 description.
TSTPLL	6	I	Test Mode (active low, internal pull-up). When this pin is tied to GND, the internal PLL is bypassed and an external 48 MHz clock is used as the reference clock.
TSTMODE	7	I	Internal Test Mode (active low, internal pull-up). When this pin is tied to GND, the Internal Test Mode is enabled.
DM	9	I/O	Upstream USB port differential Data Minus (D-), analog.
DP	10	I/O	Upstream USB port differential Data Plus (D+), analog.
RESET	12	I	System Reset (active high). Resets all internal registers, sequencers, and signals to a consistent state. Connect to GND to use the internal Power-On-Reset circuit.
nCD	15	I	Carrier-Detect signal. When low, this indicates that the modem or data set has detected the Data Carrier. nCD has no effect on the transmitter.
nDSR	18	I	Data-Set-Ready signal. When low, this indicates that the modem or data set is ready to establish a communication link. nDSR has no effect on the transmitter or receiver.
RX	19	I	UART Serial Data Input.
nRTS	20	O	Request-To-Send signal. It is set high (inactive) after a hardware reset or during internal loop-back mode. When low, this indicates that the UART is ready to exchange data.
SLCT	22	I	Peripheral/Printer Selected (internal pull-up). This pin is set high by the peripheral/printer when it is selected.
PE	23	I	Paper Empty (internal pull-up). This pin is set high by the peripheral/printer when printer paper is empty.
BUSY	24	I	Peripheral/Printer Busy (internal pull-up). This pin is set high by the peripheral/printer when the printer or peripheral is not ready to accept data.
nACK	25	I	Peripheral/Printer data Acknowledge (internal pull-up). This pin is set low by the peripheral/printer to indicate a successful data transfer has taken place.
PD7	26	I/O	Parallel printer port Data bit 7.

Pin Name	Pin	Type	Description
PD6	27	I/O	Parallel printer port Data bit 6.
TX	28	O	UART Serial Data Output.
PD5	29	I/O	Parallel printer port Data bit 5.
PD4	32	I/O	Parallel printer port Data bit 4.
PD3	33	I/O	Parallel printer port Data bit 3.
nSLCTIN	34	I/O	Peripheral/Printer Select (open-drain). Selects the peripheral/printer when it is set low.
PD2	35	I/O	Parallel printer port Data bit 2.
nINIT	36	I/O	Initialize the peripheral/printer (open drain). When set low, the peripheral/printer starts its initialization routine.
PD1	37	I/O	Parallel printer port Data bit 1.
nFAULT	38	I	Peripheral/Printer data error (internal pull-up). This pin is set low by the peripheral/printer during an error condition.
PD0	40	I/O	Parallel printer port Data bit 0.
nAUTOFDX	41	I/O	Peripheral/Printer Auto Feed (open-drain). Continuous autofed paper is selected when this pin is set low.
nSTROBE	42	I/O	Peripheral/Printer data Strobe (open drain). Data is latched into the peripheral/printer when the nSTROBE is low.
nCTS	44	I	Clear-To-Send signal. When low, this indicates that the modem or data set is ready to exchange data. nCTS has no effect on the transmitter.
nDTR	45	O	Data-Terminal-Ready signal. It is set high (inactive) after a hardware reset or during internal loop-back mode. When low, this output indicates to the modem or data set that the UART is ready to establish a communication link. nDTR has no effect on the transmitter or receiver.
nRI	46	I	Ring-In detect signal.
VOUT	48	PWR	+3.3V Voltage Regulator output.
GND	5, 8, 13, 14, 17, 21, 30, 39, 47	PWR	Power and Signal Ground.
3.3V	2, 11, 16, 31, 43	PWR	Device Supply Inputs. All should be connected to the VOUT pin. VOUT voltage is gated by RESET.
5V	1	PWR	Main Power Input. Connect to USB VBUS or local VDD.

Note: All names with “n” prefix are active low.

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USB Description

Analog Transceivers

The on-chip transceivers are connected directly to USB cables through external series resistors. They transmit and receive serial data at both full-speed (12Mbit/s) and low-speed (1.5Mbit/s) data rates. Slew rates are automatically adjusted according to the speed of the device connected and lie within the range defined in the *USB Specification Rev. 1.1*.

Serial Interface Engine

This engine implements the complete USB protocol layer including: parallel /serial conversion, synchronization pattern recognition, CRC checking/generation, bit (de)stuffing, packet identifier (PID) verification/generation, address recognition and handshake evaluation/generation.

Bit Clock Recovery

The bit clock recovery circuit recovers the clock from the incoming USB data stream using 4x over sampling. It is able to track in the presence of jitter and frequency drift as specified by the USB Specification Rev. 1.1.

3.3V Source

A 5V to 3.3V DC-DC regulator is integral to the chip relieving the need for a +3.3V source. It supplies the analog transceivers and internal logic and can be used to supply the 1.5k Ω pull-up resistor on the DP line of the upstream connection.

PLL Clock Multiplier

An integral Phase-Locked Loop (PLL) performs 6 to 48MHz clock multiplication and requires no external components except the crystal. This allows for the use of low-cost 6MHz crystals which reduce high frequency radiated Electro-Magnetic Interference (EMI).

Host Requests

All standard USB requests from the host are handled via Control Endpoint-0. The Control Endpoint can handle a maximum of 8 Bytes per transfer.

This table shows the supported standard USB requests.

Note: the USB data transmission order is Least Significant Bit (LSB) first. In the following tables Multi-Byte variables are displayed least significant Byte first.

Standard USB Requests

RequestName	bmRequestType Byte 0 [7:0] (bin)	bRequest Byte 1 (hex)	wValue Byte 2, 3 (hex)	wIndex Byte 4, 5 (hex)	wLength Byte 6, 7 (hex)	Data
Address						
Set Address	X000 0000	05	address**	00,00	00,00	none
Configuration						
Get Configuration	1000 0000	08	00,00	00,00	01,00	Configuration Value = 0x01
Set Configuration-0	X000 0000	09	00,00	00,00	00,00	none
Set Configuration-1	X000 0000	09	01,00	00,00	00,00	none
Descriptor						
Get Configuration Descriptor	1000 0000	06	00,02	00,00	length***	Configuration, Interface, and Endpoint Descriptors
Get Device Descriptor	1000 0000	06	00,01	00,00	length***	Device Descriptor
Feature						
Clear Feature (REMOTE_WAKEUP)	X000 0000	01	01,00	00,00	00,00	none
Clear Endpoint (1) Feature (HALT/STALL)	X000 0010	01	00,00	81,00	00,00	none
Status						
Get Device Status	1000 0000	00	00,00	00,00	02,00	Device Status
Get Interface Status	1000 0001	00	00,00	00,00	02,00	zero
Get Endpoint (0) Status	1000 0010	00	00,00	00/80, 00*	02,00	Endpoint-0 Status
Get Endpoint (1) Status	1000 0010	00	00,00	81,00	02,00	Endpoint-1 Status

* The MSB specifies endpoint direction: 0 = OUT, 1 = IN. Either value is accepted.

** Device Address: 0 to 127

*** Returned Value (in Bytes)

Standard USB Descriptors

These are the supported Standard USB Descriptors:

- Device
- Configuration
- Interface
- Endpoint

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Device Descriptors

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	12	Descriptor Length = 18 Bytes
1	bDescriptorType	1	01	Type = DEVICE
2	bcdUSB	2	10,01	USB Specification Rev-1.1
4	bDeviceClass	1	FF	Vendor Class
5	bDeviceSubClass	1	00	n/a
6	bDeviceProtocol	1	FF	Vendor Class
7	bMaxPacketSize0	1	08	Packet Size = 8 Bytes
8	idVendor	2	10,97	the MosChip Vendor-ID (9710)
10	idProduct	2	15,77	the MCS7715 Product-ID
12	bcdDevice	2	00,01	the silicon revision (1.0)
14	iManufacturer	1	00	no manufacturer string
15	iProduct	1	00	no product string
16	iSerialNumber	1	00	no serial number string
17	bNumConfigurations	1	01	one configuration

Configuration Descriptors

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	09	Descriptor Length = 9 Bytes
1	bDescriptorType	1	02	Type = CONFIGURATION
2	wTotalLength	2	35,00	Combined Length of Configuration, + Interface, + all Endpoint Descriptors (53 Bytes)
4	bNumInterfaces	1	01	one Interface
5	bConfiguration	1	01	Configuration Value = 1
6	iConfiguration	1	00	no configuration string
7	bmAttributes	1	A0	Bus-Powered with remote wake-up
8	MaxPower	1	32	100mA default

Interface Descriptors

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	09	Descriptor Length = 9 Bytes
1	bDescriptorType	1	04	Type = INTERFACE
2	bInterfaceNumber	1	00	n/a
3	bAlternateSetting	1	00	no alternate setting
4	bNumEndpoints	1	05	five Endpoints
5	bInterfaceClass	1	FF	Vendor Class
6	bInterfaceSubClass	1	00	n/a
7	bInterfaceProtocol	1	FF	Vendor Class
8	bInterface	1	00	no interface string

Endpoint Descriptions

There are five end points apart from the Control Endpoint

Endpoint	Type	Function	Size
0	Control Endpoint	Default Functionality	
1	Bulk-In	Parallel Printer Port	32Bytes
2	Bulk-Out	Parallel Printer Port	32 Bytes
3	Bulk-In	Serial Port	64 Bytes
4	Bulk-Out	Serial Port	32 Bytes
5	Interrupt	Status Endpoint	4 Bytes

Endpoint Descriptor #1 Bulk-In (Parallel Port)

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	07	Descriptor Length = 7 Bytes
1	bDescriptorType	1	05	Type = ENDPOINT
2	bEndpointAddress	1	81	Endpoint-1, direction: IN
3	bmAddress	1	02	Bulk Endpoint
4	wMaxPacketSize	2	20,00	Packet Size = 32 Bytes
6	bInterval	1	FF	Polling Interval (255mS)

Endpoint Descriptor #2 Bulk-Out (Parallel Port)

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	07	Descriptor Length = 7 Bytes
1	bDescriptorType	1	05	Type = ENDPOINT
2	bEndpointAddress	1	02	Endpoint-2, direction: OUT
3	bmAddress	1	02	Bulk Endpoint
4	wMaxPacketSize	2	20,00	Packet Size = 32 Bytes
6	bInterval	1	FF	

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**Endpoint
Descriptor #3
Bulk-In
(Serial Port)**

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	07	Descriptor Length = 7 Bytes
1	bDescriptorType	1	05	Type = ENDPOINT
2	bEndpointAddress	1	83	Endpoint-3, direction: IN
3	bmAddress	1	02	Bulk Endpoint
4	wMaxPacketSize	2	40,00	Packet Size = 64 Bytes
6	bInterval	1	01	Polling Interval (1mS)

**Endpoint
Descriptor #4
Bulk-Out
(Serial Port)**

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	07	Descriptor Length = 7 Bytes
1	bDescriptorType	1	05	Type = ENDPOINT
2	bEndpointAddress	1	04	Endpoint-4, direction: OUT
3	bmAddress	1	02	Bulk Endpoint
4	wMaxPacketSize	2	20,00	Packet Size = 32 Bytes
6	bInterval	1	FF	

Endpoint Descriptor #5 Status Endpoint

Offset (Bytes)	Field Name	Size (Bytes)	Value (hex)	Comments
0	bLength	1	07	Descriptor Length = 7 Bytes
1	bDescriptorType	1	05	Type = ENDPOINT
2	bEndpointAddress	1	87	Endpoint-7, direction: IN
3	bmAddress	1	03	Interrupt Endpoint
4	wMaxPacketSize	2	04,00	Packet Size = 4 Bytes
6	bInterval	1	01	Polling Interval (1mS)

Status Endpoint:

The Status Endpoint returns 4 Bytes every 1 millisecond. These four Bytes are status information of the Parallel Printer port and the Serial port.

- Byte-1: Interrupt Identification Register of the Serial port (IIR)
- Byte-2: Reserved (Unused)
- Byte-3: Device Status Register of the Parallel Printer port (DSR)
- Byte-4: FIFO status of both the Parallel Printer port and the Serial port.

Description for Byte-4 of Status Endpoint.

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Reserved	Reserved	SerInFifo Status	SerOutFifo Status	ParOutFifo Empty	ParOutFifo Full	ParInFifo Empty	ParInFifo Full

Bit	Description
ParInFifo Full	1 Indicates the Bulk-In FIFO is full. (Parallel Printer Port)
ParInFifo Empty	1 Indicates the Bulk-In FIFO is empty. (Parallel Printer Port)
ParOutFifo Full	1 Indicates the Bulk-Out FIFO is full. (Parallel Printer Port)
ParOutFifo Empty	1 Indicates the Bulk-Out FIFO is empty. (Parallel Printer Port)
SerOutFifo Status	1 Indicates the Bulk-Out FIFO is empty. 0 indicates the Bulk-Out FIFO is filled with Tx Data. (Serial Port)
SerInFifo Status	1 indicates the Bulk-In FIFO is filled with Rx Data. 0 indicates the Bulk-In FIFO is empty. (Serial Port)

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USB Vendor Specific Commands:

The purpose of the vendor commands is to configure the Serial and Parallel Printer ports.

The following tables provide information for the Vendor Specific Commands.

PARALLEL PRINTER PORT

Get Application
Vendor Specific Command
(Parallel Printer Port)

BmrequestType	Brequest	Wvalue	Windex	Wlength	Register Name
0xC0	0x0D	0x01 _{xx}	0x0000	0x0001	PP_DPR
0xC0	0x0D	0x01 _{xx}	0x0001	0x0001	PP_DSR
0xC0	0x0D	0x01 _{xx}	0x0002	0x0001	PP_DCR
0xC0	0x0D	0x01 _{xx}	0x0008	0x0001	PP_C_FIFO
0xC0	0x0D	0x01 _{xx}	0x0008	0x0001	PP_CONF_A
0xC0	0x0D	0x01 _{xx}	0x0009	0x0001	PP_CONF_B
0xC0	0x0D	0x01 _{xx}	0x000A	0x0001	PP_ECR

Set Application
Vendor Specific Command
(Parallel Printer Port)

BmrequestType	Brequest	Wvalue	Windex	Wlength	Register Name
0x40	0x0E	0x01 _{xx}	0x0000	0x0000	PP_DPR
0x40	0x0E	0x01 _{xx}	0x0001	0x0000	PP_DSR
0x40	0x0E	0x01 _{xx}	0x0002	0x0000	PP_DCR
0x40	0x0E	0x01 _{xx}	0x0008	0x0000	PP_C_FIFO
0x40	0x0E	0x01 _{xx}	0x0008	0x0000	PP_CONF_A
0x40	0x0E	0x01 _{xx}	0x0009	0x0000	PP_CONF_B
0x40	0x0E	0x01 _{xx}	0x000A	0x0000	PP_ECR

SERIAL PORT

Get Application
Vendor Specific Command
(Serial Port)

BmrequestType	Brequest	Wvalue	Windex	Wlength	Register Name
0xC0	0x0D	0x02 _{xx}	0x0000	0x0001	SP_RHR
0xC0	0x0D	0x02 _{xx}	0x0001	0x0001	SP_IER
0xC0	0x0D	0x02 _{xx}	0x0002	0x0001	SP_IIR
0xC0	0x0D	0x02 _{xx}	0x0003	0x0001	SP_LCR
0xC0	0x0D	0x02 _{xx}	0x0004	0x0001	SP_MCR
0xC0	0x0D	0x02 _{xx}	0x0005	0x0001	SP_LSR
0xC0	0x0D	0x02 _{xx}	0x0006	0x0001	SP_MSR
0xC0	0x0D	0x02 _{xx}	0x0007	0x0001	SP_SPR
0xC0	0x0D	0x02 _{xx}	0x0000	0x0001	SP_DLL
0xC0	0x0D	0x02 _{xx}	0x0001	0x0001	SP_DLM

Set Application
Vendor Specific Command
(Serial Port)

BmrequestType	Brequest	Wvalue	Windex	Wlength	Register Name
0x40	0x0E	0x02 _{xx}	0x0000	0x0000	SP_THR
0x40	0x0E	0x02 _{xx}	0x0001	0x0000	SP_IER
0x40	0x0E	0x02 _{xx}	0x0002	0x0000	SP_FCR
0x40	0x0E	0x02 _{xx}	0x0003	0x0000	SP_LCR
0x40	0x0E	0x02 _{xx}	0x0004	0x0000	SP_MCR
0x40	0x0E	0x02 _{xx}	0x0005	0x0000	SP_LSR
0x40	0x0E	0x02 _{xx}	0x0006	0x0000	SP_MSR
0x40	0x0E	0x02 _{xx}	0x0007	0x0000	SP_SPR
0x40	0x0E	0x02 _{xx}	0x0000	0x0000	SP_DLL
0x40	0x0E	0x02 _{xx}	0x0001	0x0000	SP_DLM

Vendor Specific Command Parameters

Brequest: specifies whether to Read or Write

0x0E = write to the application register.

0x0D = read from the application register.

Wvalue: Specifies the Application Number.

0x0100 is the application number for the Parallel Printer port

0x0200 is the application number for the Serial port

0x0000 is the application number provided for accessing the other control registers to control the Parallel Printer port and Serial port (i.e. Enabling the Higher Baud Rates, enabling the Auto hardware Flow Control, Setting the clock frequency, etc.)

xx specifies the Byte value to be written into the register.

Windex: Is the offset of the register to Read/Write.

Wlength: Is the length of the data we are going to read or write.

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UART Register Set:

The UART has 10 registers. Mapping is dependent on the Line Control Register (LCR).

Register Name	Offset	R/W	Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
THR	0	W	Data to be transmitted (Transmitting Holding Register)							
RHR	0	R	Data to be received (Receiver Holding Register)							
IER	1	R/W	Reserved			Sleep Mode	Modem Interrupt Mask	Rx Stat Interrupt Mask	THRE Interrupt Mask	RxRdy Interrupt Mask
FCR	2	W	RHR Trigger Level		Reserved		Reserved	Flush THR	Flush RHR	FIFO Enable
ISR	2	R	FIFOs Enabled		Reserved		Interrupt Priority			Interrupt Pending
LCR	3	R/W	DLE	Tx Break	Force Parity	Odd/Even Parity	Parity Enable	Stop Bits	Data Length	
MCR	4	R/W	Reserved		RTS/CTS Flow Control	Loop	Unused		RTS	DTR
LSR	5	R	Data Error	Tx Empty	THR Empty	Rx Break	Framing Error	Parity Error	Overrun	RxRdy
MSR	6	R	DCD	RI	DSR	CTS	Delta DCD	TERI	Delta DSR	Delta CTS
SPR	7	R/W	Scratch Pad Register							

Additional Standard Registers - these are accessed when LCR[7] = 1

DLL	0	R/W	Divisor Latch bits[7:0]							
DLM	1	R/W	Divisor Latch bits[15:8]							

Register: THR
Description: Data to be transmitted
Offset: 000
Permissions: Write
Access Condition: LCR[7] = 0, only write condition can access this register

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Data to be transmitted							

Register: RHR
Description: Data to be received
Offset: 000
Permissions: Read
Access Condition: LCR[7] = 0, only read condition can access this register

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Data to be received							

Interrupt Enable Register:

Serial channel interrupts are enabled using the Interrupt Enable Register (IER).

Register: IER
Description: Interrupt Enable Register
Offset: 001
Permissions: Read/Write

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Reserved			Sleep Mode	Modem Interrupt Mask	Rx Stat Interrupt Mask	THRE Interrupt Mask	RxRdy Interrupt Mask

Bit	Name	Description
0	RxRdy Interrupt Mask	Logic 0 = Disable the Receiver Ready Interrupt Logic 1 = Enable the Receiver Ready Interrupt
1	THRE Interrupt Mask	Logic 0 = Disable the Transmitter Ready Interrupt Logic 1 = Enable the Transmitter Ready Interrupt
2	Rx Stat Interrupt Mask	Logic 0 = Disable the Receiver Status Interrupt (Normal Mode) Logic 1 = Enable the Receiver Status Interrupt (Normal Mode)
3	Modem Interrupt Mask	Logic 0 = Disable the Modem Status Interrupt Logic 1 = Enable the Modem Status Interrupt
4	Sleep Mode	Logic 0 = Disable Sleep-Mode Logic 1 = Enable Sleep-Mode (the internal clock of the channel is switched off)
5	Reserved	Reserved
6	Reserved	Reserved
7	Reserved	Reserved

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FIFO Control Register:

The FCR controls the UART behavior in various modes.

Register: FCR
Description: FIFO Control Register
Offset: 010
Permissions: Write

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
RHR Trigger Level		Reserved		Reserved	Flush THR	Flush RHR	Enable FIFO

Bit	Name	Description
0	Enable FIFO Mode	Logic 0 = Byte Mode Logic 1 = FIFO Mode
1	Flush RHR	Logic 0 = No change Logic 1 = Flushes the contents of RHR. This is operative only in FIFO Mode. The RHR is automatically flushed whenever changing between Byte Mode and FIFO Mode. The bit will return to zero after clearing the FIFOs.
2	Flush THR	Logic 0 = No change Logic 1 = Flushes the content of the THR, in the same manner as FCR[1] does the RHR
3	Reserved	Reserved
5, 4	Reserved	Reserved
7, 6	RHR Trigger Level	See the table below.

FCR[7:6] RHR Trigger Level:

In 550 mode, the receiver FIFO trigger levels are defined using FCR[7:6]. The interrupt trigger level & flow control trigger level where appropriate are defined by L2 in the table below. L1 defines lower flow control trigger levels that introduce a hysteresis element in hardware RTS/CTS flow control.

In Byte Mode (450 Mode) the trigger levels are all set to 1.

FCR[7:6]	550 Mode (FIFO = 16)	
	L1	L2
2'b00	1	1
2'b01	1	4
2'b10	1	8
2'b11	1	14

Interrupt Status Register:

The source of the highest priority interrupt pending is indicated by the contents of the Interrupt Status Register (ISR). There are five sources of interrupts, and four levels of priority (1 is the highest) as tabulated below.

Level	Interrupt Source	ISR[5:0]
-	No interrupt pending	6'b000001
1	Receiver Status Error or address bit detected in 9-bit mode	6'b000110
2a	Receiver Data Available	6'b000100
2b	Receiver Time Out	6'b001100
3	Transmitter THR Empty	6'b000010
4	Modem Status Change	6'b000000

Note: ISR[0] indicates whether any interrupt is pending

Register: ISR
Description: Interrupt Status Register
Offset: 010
Permissions: Read

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
FIFOs Enabled		Interrupt Priority (Enhanced Mode)		Interrupt Priority (All Modes)			Interrupt Pending

Interrupt Descriptions:

Level1: Receiver Status Error

Normal Mode: This interrupt is active whenever any of the LSR[1], LSR[2], LSR[3] or LSR[4] are set. These flags are cleared following a read of the LSR. The interrupt is masked with IER[2].

Level 2a: Receiver Data Available

The interrupt is active whenever the receiver FIFO level is above the interrupt trigger level.

Level 2b: Receiver Time-Out

A receiver time out event, (which may cause an interrupt) will occur when all of the following conditions are true:

- The UART is in the FIFO Mode.
- There is data in the RHR
- There has been no read of the RHR for a period of time greater than the timeout period. The time-out period of time is greater than the time out period. *The time out period is four times the character period (including start & stop bits) measured from the centre of the first stop bit of the first data item received.*

Reading the first data item in RHR clears this interrupt.

Level 3: Transmitter Empty

This interrupt is set when the transmit FIFO level falls below the trigger level. It is cleared on the ISR read to Level-3 interrupt or by writing more data to the THR so that the trigger level is exceeded.

Level 4: Modem Change

This interrupt is set by the modem change flag (MSR[0], MSR[1], MSR[2] or MSR[3]) becoming active due to changes in the input modem lines. This interrupt is cleared following the read of the MSR register.

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Line Control Register:

The LCR specifies the data format that is common to both transmitter and receiver.

Register: LCR
Description: Line Control Register
Offset: 011
Permissions: Read/Write
Access Condition: LCR[7] = 0

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
DLE	Tx Break	Force Parity	Odd/Even Parity	Parity Enable	Number of Stop Bits	Data Length	

LCR[1:0]: Determines the data length of serial characters.

LCR[1:0]	Data Length
2'b00	5 bits
2'b01	6 bits
2'b10	7 bits
2'b11	8 bits

LCR[2]: Defines the number of stop bits per serial character.

LCR[5:3]: The selected parity type will be generated during transmission and checked by the receiver, which may produce a parity error as a result. In 9-bit mode parity is disabled and LCR[5:3] are ignored.

LCR[2]	Data Length	Stop Bits
0	5,6,7,8	1
1	5	1.5
1	6,7,8	2

LCR[6]: Transmission Break

Logic 0: Break transmission disabled

Logic 1: Forces the transmitter data output (SOUT) low to alert the communications channel. It is the responsibility of the software driver to ensure that the break duration is longer than the character period for it to be recognized remotely as a break rather than data.

LCR[5:3]	Parity Type
3'bxx0	No parity
3'b001	Odd parity
3'b011	Even parity
3'b101	Parity bit forced to 1
3'b111	Parity bit forced to 0

LCR[7]: Divisor Latch Enable

Logic 0: Accesses to DLL and DLM registers disabled

Logic 1: Accesses to DLL and DLM registers enabled

Line Status Register:

This register provides the status of the data transfer to the CPU.

Register: LSR
Description: Line Status Register
Offset: 101
Permissions: Read
Access Condition: LCR[7] = 0, ACR[6] = 0

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Data Error	Tx Empty	THR Empty	Rx Break	Framing Error	Parity Error	Overrun	RxRdy

Bit	Name	Description
0	RHR Data Available	Logic 0 = RHR is empty Logic 1 = RHR is not empty, data is available to be read
1	RHR Overrun	Logic 0 = No overrun error Logic 1 = Data was received when the RHR was full, An overrun has occurred. The error is flagged when the data would normally have been transferred to the RHR.
2	Received Data Parity Error	Logic 0 = No parity error in received data, or 9th bit is "0" in 9-bit mode. Logic 1 = Data has been received that did not have correct parity
3	Received Data Framing Error	Logic 0 = No framing error Logic 1 = data has been received with an invalid stop bit.
4	Received Break Error	Logic 0 = No receiver break error Logic 1 = the receiver received a break error
5	THR Empty	Logic 0 = Transmitter FIFO is not empty Logic 1 = Transmitter FIFO is empty
6	Transmitter & THR Empty	Logic 0 = The transmitter is not idle Logic 1 = THR is empty & the transmitter has completed the character in the shift register and is in the idle mode
7	Receiver Data Error	Logic 0 = Either there are no receiver data errors in the FIFO, or it was cleared by earlier read of LSR Logic 1 = At least one parity error, framing error or break indication in the FIFO.

Note : A break condition occurs when the SIN line goes low and stays low through out the start, data, parity & first stop bits. One zero character associated with break flag set will be transferred to the RHR and the receiver will then wait until the SIN line returns high. The LSR[4] flag break flag is set when this data item gets to the top of the RHR and it is cleared following the read to the LSR.

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Modem Control Register:

Register: MCR
Description: Modem Control Register
Offset: 100
Permissions: Read/Write

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
550 Mode							
Unused	CTS/RTS Flow Control	Internal Loop Back Enable	Out2 (Interrupt Enable)	Out1	RTS	DTR	

Bit	Name	Description
0	DTR	Logic 0 = Forces DTR# output to inactive (high) Logic 1 = Forces DTR# output to active (low)
1	RTS	Logic 0 = Forces RTS# output to inactive (high) Logic 1 = Forces RTS# output to active (low)
2	Out1	Unused
3	Out2	Unused
4	Internal Loop Back Enable	Logic 0 = Normal operating mode Logic 1 = Enable Local Loop-Back Mode
5	CTS/RTS flow control	Logic 0 = CTS/RTS flow control Disabled in 550-Mode Logic 1 = CTS/RTS flow control Enabled in 550-Mode
6	Unused	Unused
7	Unused	Unused

Modem Status Register:

This register provides the status of the modem control lines to CPU.

Register: MSR
Description: Modem Status Register
Offset: 110
Permissions: Read

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
DCD	RI	DSR	CTS	Delta DCD	Trailing Edge RI	Delta DSR	Delta CTS

Bit	Name	Description
0	Delta CTS	Logic 0 = no change in the CTS signal Logic 1 = indicates that the CTS input has changed since the last time the MSR was read
1	Delta DSR	Logic 0 = no change in the DSR signal Logic 1 = indicates that the DSR input has changed since the last time the MSR was read
2	Trailing Edge RI	Logic 0 = no change in the RI signal Logic 1 = indicates that the RI input has changed from low to high since the last time the MSR was read
3	Delta DCD	Logic 0 = no change in the DCD signal Logic 1 = indicates that the DCD input has changed since the last time the MSR was read
4	CTS	Logic 0 = CTS# line is 1 Logic 1 = CTS# line is 0
5	DSR	Logic 0 = DSR# line is 1 Logic 1 = DSR# line is 0
6	RI	Logic 0 = RI# line is 1 Logic 1 = RI# line is 0
7	DCD	Logic 0 = DCD# line is 1 Logic 1 = DCD# line is 0

Scratch Pad Register:

The scratch pad register does not effect operation of the rest of the UART in any way and can be used for the temporary data storage.

Register: SPR
Description: Scratch Pad Register
Offset: 111
Permissions: Read/Write

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Scratch Pad Register							

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Divisor Latch Registers:

The divisor latch registers (DLL & DLM) are used to program the baud rate divisor. This is a value between 1 and 65535 by which the input clock is divided in order to generate serial Baud Rates. After a hardware Reset, the Baud Rate used by the transmitter & receiver is given by:

$$\text{Baud Rate} = \text{Input Clock} / 16 * \text{Divisor}$$

where divisor is given by: $(256 * \text{DLM}) + \text{DLL}$

Note: More flexible Baud Rate generation options are also available. These require the use of Advanced Features in other registers however.

Register: DLL
Description: Divisor Latch Register
Offset: 000
Permissions: Read/Write
Access Condition: LCR[7] =1, Address = 000

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Least significant Byte for divisor latch							

Register: DLM
Description: Divisor Latch Register
Offset: 001
Permissions: Read/Write
Access Condition: LCR[7] =1, Address = 001

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Most significant Byte for divisor latch							

**Baud Rate Generator
Programming Table**

Baud Rate	DLM (Hex)	DLL (Hex)
115.2K	00	01
57.6K	00	02
38.4K	00	03
19.2K	00	06
9600	00	0C
2400	00	30
1200	00	60
600	00	C0
300	01	80
150	03	00
50	09	00

Master Reset Values

Register	BIT-7	BIT-6	BIT-5	BIT-4	BIT-3	BIT-2	BIT-1	BIT-0
RHR	0	0	0	0	0	0	0	0
THR	X	X	X	X	X	X	X	X
IER	0	0	0	0	0	0	0	0
FCR	0	0	0	0	0	0	0	0
IIR	0	0	0	0	0	0	0	1
LCR	0	0	0	0	0	0	0	0
MCR	0	0	0	0	0	0	0	0
LSR	0	1	1	0	0	0	0	0
MSR	X	X	X	X	0	0	0	0
SPR	0	0	0	0	0	0	0	0

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Parallel Printer Port Register Descriptions

Data Register

The Data Register is cleared at initialization by RESET. During a write operation, the contents of this register are buffered and output onto the PD7-PD0 ports. During a read operation PD7-PD0 ports are buffered and output to the host CPU.

Register: PP_DPR
Description: Parallel Printer Data Register
Offset: 000
Permissions: Read/Write
Access Condition: Application Number = 0x0100

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Parallel Printer Data							

Device Status Register

The bits of the status register are defined as follows:

Register: DSR
Description: Device Status Register
Offset: 001
Permissions: Read
Access Condition: Application Number = 0x0100

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
nBUSY	nACK	PE	SLCT	nFAULT	Unused	Unused	Unused

Bit	Name	Description
0	Unused	Not used, set to 0
1	Unused	Not used, set to 0
2	Unused	Not used, set to 0
3	nFAULT	Logic 0 = Printer reports an error condition exists. Logic 1 = Normal operation.
4	SLCT	Logic 0 = Printer is off line. Logic 1 = Printer is on line.
5	PE	Logic 0 = Normal operation Logic 1 = Paper end/empty is detected
6	nACK	Logic 0 = State of the nACK pin (nACK = Low). Logic 1 = State of the nACK pin (nACK = High).
7*	nBUSY	Logic 0 = BUSY pin is high, printer is not ready to take data. Logic 1 = BUSY pin is low, printer is ready to take data.

Note: Bit-7 (nBUSY) in this register is logically inverted from the state of the electrical signal appearing at the physical device pin. When the printer is BUSY, this bit will read back as a zero.

Device Control Register

Register: DCR
Description: Device Control Register
Offset: 002
Permissions: Read/Write
Access Condition: Application Number = 0x0100

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Unused	Unused	DIR	Unused	SLCTIN	nINIT	AUTOFD	STROBE

Bit	Name	Description
0*	STROBE	Logic 0 = Sets the nSTROBE pin to high. Logic 1 = Sets the nSTROBE pin to low. PD7-PD0 data are latched into printer
1*	AUTOFD	Logic 0 = Sets the nAUTOFDX pin to high. No auto feed function. Logic 1 = Sets the nAUTOFDX pin to low. Printer generates auto line feed after each line is printed.
2	nINIT	Logic 0 = Peripheral/printer starts its initialization routine. Logic 1 = Normal Operation.
3*	SLCTIN	Logic 0 = Sets the nSLCTIN pin to high. Printer is not selected. Logic 1 = Sets the nSLCTIN pin to low. Selects the printer.
4	Unused	Not used, set to 0
5	DIR	Logic 0 = PD7-PD0 pins are configured for output mode. Logic 1 = PD7-PD0 pins are configured for input mode.
6	Unused	Not used, set to 0.
7	Unused	Not used, set to 0.

Note: Three bits (0, 1, & 3) of this register are logically inverted from the state of the electrical signals appearing at the physical device pins they control. The physical pins for these three bits are all Active-Low signals, so writing a “one” in this register will enable or activate the desired function.

The physical pin associated with Bit-2 (nINIT) of this register is also an Active-Low electrical signal. This bit is not inverted however, so in order to start the Initialization process, this bit must be set LOW.

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Extended Control Register (ECR)

This register controls the Parallel Port mode selection operation.

Register: PP_ECR
Description: Parallel Printer Port Extended Control Register
Offset: 0x0A
Permissions: Read/Write
Access Condition: Application Number = 0x0100

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Parallel Port Mode			Reserved	Reserved	Reserved	Reserved	Reserved

Bit-7	Bit-6	Bit-5	Operating Mode
0	0	0	SPP
0	0	1	Nibble
0	1	0	CB-FIFO mode
0	1	1	Not Used
1	0	0	Not Used
1	0	1	Not used
1	1	0	Not Used
1	1	1	Not Used

Mode Changes

After a hardware reset Nibble Mode is selected as the default mode. It is required to select mode 000 or 001 before any other mode configuration.

Mode “000”

SPP/Centronics/Compatible Mode

Forward direction only. The direction bit is forced to “0” and PD7-PD0 are set to the output direction. The Parallel Port is under software control. This mode defines the protocol used by most PCs to transfer data to a printer. It is commonly called the “Centronics” mode and is the method utilized with the Standard Parallel Printer port. Data is placed on the PD7-PD0 ports, and the printer status is checked via the DSR register. If no error condition is flagged and the printer is not busy, software toggles the nSTROBE pin to latch the PD7-PD0 data into the printer. This operating cycle continues when the printer/peripheral issues the data acknowledge signal (pulses the ACK and nBUSY pins).

Mode “001”

Nibble Mode

The Nibble Mode is the most common way to get reverse channel data from the printer or peripheral. This mode is usually combined with the SPP Mode or a proprietary forward channel mode to create a Bi-Directional channel. In this mode printer status bits are used as Nibble bits.

Pin	Data Bit
BUSY	Bit-7
PE	Bit-6
SLCT	Bit-5
nFAULT	Bit-4
BUSY	Bit-3
PE	Bit-2
SLCT	Bit-1
nFAULT	Bit-0

Bit Order for Nibble Mode

Mode “010”

FIFO Output Mode

In this mode, Bytes written to the FIFO are transmitted automatically using the SPP/Centronics standard protocol.

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Vendor Specific Command Registers:

There are three vendor specific registers which are used to tune the behavior and performance of the UART and Parallel Port. They are as follows

- SP_REG
- PP_REG
- SP_CONTROL_REG

SP_REGISTER:

This register is used for internal debugging of UDC controller & bridge circuitry. This enables the designer to pin point the problem in the design. This register also enables the hardware flow control. This register has bits which clear the Bulk-In & Bulk-Out FIFOs. There is a bit which resets the UART. There are bits which control the input clock fed to the UART, providing options for higher Baud Rates.

Register: SP_REG
Description: Serial Port Register
Offset: 0x01
Permissions: Read/Write
Access Condition: Application Number = 0x0000

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
UART_Reset	Clk_UART_Select		Sp_bi_clear	Sp_bo_clear	Ser_line_err_ctl_en		Udc_loop

Bit	Description
Udc_loop	When enabled, loops the data from the Bulk-Out FIFO to the Bulk-In FIFO.
Ser_line_err_ctl_en	When enabled, will not allow the data from the UART to be written into the Bulk-In FIFO if there are any errors in the received data.
Sp_bo_clear	Reset the Bulk-Out FIFO
Sp_bi_clear	Reset the Bulk-In FIFO
Clk_UART_Select	Changes the clock fed to UART as shown in the table below
UART_Reset	Resets the UART

Clk_UART_Select: Changes the clock fed to the Serial Port as shown in the table below.

Option	Input Clock Frequency
3'b000	12 MHz
3'b001	6 MHz
3'b010	3 MHz
3'b011	1.5 MHz
3'b100	0.75 MHz

PP_REGISTER:

This register is used for internal debugging of UDC controller & bridge circuitry. There is a bit which resets the Parallel Printer port. There are bits which control the input clock fed to the Parallel Printer port.

Register: PP_REG
Description: Parallel Printer Port Register
Offset: 0x04
Permissions: Read/Write
Access Condition: Application Number = 0x0000

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
pp_reset	clk_freq_select			pp_bi_clear	pp_bo_clear	Reserved	udc_loop

Bit	Description
udc_loop	When enabled, loops the data from the Bulk-Out FIFO to the Bulk-In FIFO.
Reserved	Reserved
pp_bo_clear	Reset the Bulk-Out FIFO
pp_bi_clear	Reset the Bulk-In FIFO
clk_freq_select	Changes the clock fed to the Parallel Printer port.
pp_reset	Resets the Parallel Printer port

pp reset: This bit will reset the Parallel Printer port. When this bit is a 1 the Parallel Printer port is under the Reset process. Whenever the frequency is to be changed, first set the Reset bit, change the clk_freq, and finally clear the Reset bit to 0.

clk_freq_select: Changes the clock fed to the Parallel Printer port as shown in the table below.

Option	Input Clock Frequency
3'b000	12 MHz
3'b001	6 MHz
3'b010	3 MHz
3'b011	1.5 MHz
3'b100	0.75 MHz

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SP_CONTROL_REGISTER:

The Control register is used for controlling the Auto RTS/CTS flow control of the Serial Port.

Register: SP_CONTROL_REG
Description: Control Register for Serial Port
Offset: 0x08
Permissions: Read/Write
Access Condition: Application Number = 0x0000

Bit[7]	Bit[6]	Bit[5]	Bit[4]	Bit[3]	Bit[2]	Bit[1]	Bit[0]
Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	sp_autoflow_ctrl_en

Bit	Description
sp_autoflow_ctrl_en	This bit is used for enabling the hardware flow control for the Serial port.
Reserved	Reserved

Electrical Characteristics

Absolute Maximum Ratings

Supply Voltage	6 Volts
Input Voltage (I/O)	-0.3 to $V_{CC} + 0.3$
Storage Temperature	-60° C to +150° C

Recommended Operating Conditions

Supply Voltage	4.5 to 5.5 Volts
Input Voltage (I/O)	0 to 5.5 Volts
Ambient Operating Temperature (free air)	0° C to +70° C
Junction Operating Temperature	0° C to +115° C

Static Characteristics (Supply Pins)

V_{CC} = 4.5V to 5.5V; GND = 0V; Temp = 0 to +70° C; unless otherwise specified

Symbol	Parameter	Conditions	Min	Typical	Max	Unit
V_{reg} (3.3V)	Regulated Supply Voltage		3.0	3.3	3.6	V
I_{CC}	Operating Supply Current		-	18	-	mA

Static Characteristics

V_{CC} = 4.5V to 5.5V; GND = 0V; Temp = 0 to +70° C; unless otherwise specified

Symbol	Parameter	Conditions	Min	Typical	Max	Unit
V_{IL}	LOW Level Input Voltage		-	-	0.3* V_{CC}	V
V_{IH}	HIGH Level Input Voltage		0.7* V_{CC}	-	-	V
$V_{th}(LH)$	Positive going Threshold Voltage		-	3.22	-	V
$V_{th}(HL)$	Negative going Threshold Voltage		-	1.84	-	V
I_{LI}	Input Leakage Current		-	-	±1	µA
I_{OZ}	Tri-State Leakage Current		-	-	±10	µA
V_{OL}	Output Voltage (Low)		-	-	0.4	V
V_{OH}	Output Voltage (High)		3.5	-	-	V

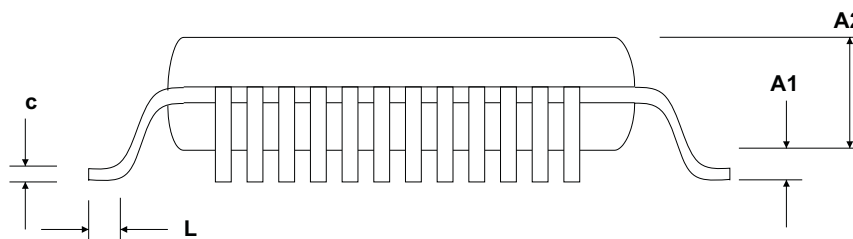
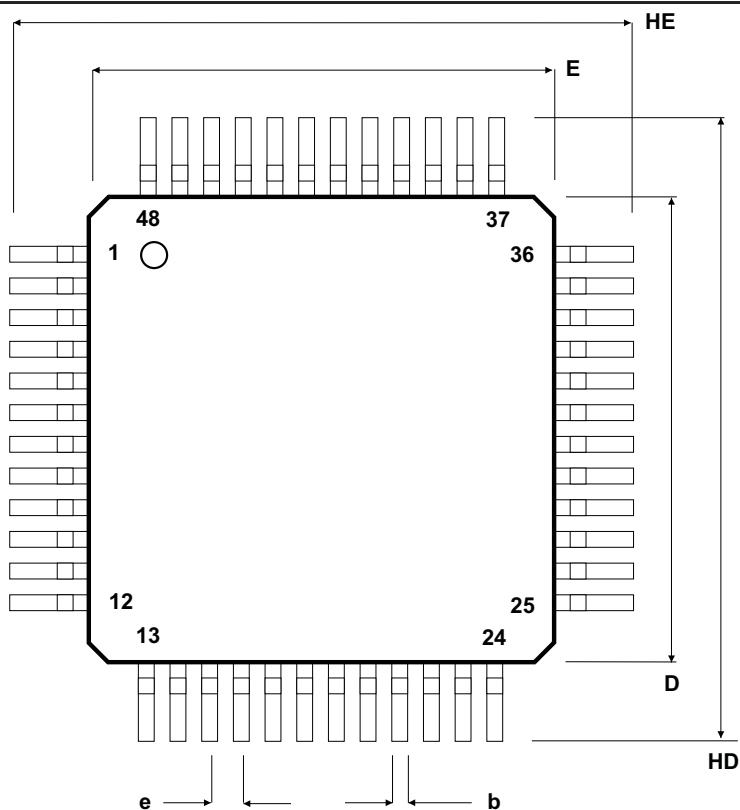
Dynamic Characteristics – Analog I/O Pins (DP, DM); Full-Speed Mode

V_{CC} = 4.5V to 5.5V; GND = 0V; Temp = 0 to +70° C; unless otherwise specified

Symbol	Parameter	Condition	Min	Typical	Max	Unit
T_{FR}	Rise Time	$C_L = 50pF$ 10% to 90% of $ V_{OH} - V_{OL} $	4	-	20	nS
T_{FF}	Fall Time	$C_L = 50pF$ 10% to 90% of $ V_{OH} - V_{OL} $	4	-	20	nS

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**48-Pin QFP
Package Dimensions**

SYMBOL	MILLIMETERS			INCHES		
	MIN	TYPICAL	MAX	MIN	TYPICAL	MAX
A1	0.05		0.15	0.002		0.006
A2	1.35		1.45	0.053		0.057
b	0.17		0.27	0.007		0.011
c	0.09		0.20	0.004		0.008
e		0.50			0.0197	
L	0.45		0.75	0.018		0.030
HD	8.80		9.20	0.346		0.362
D	7.20		6.80	0.283		0.268
HE	8.80		9.20	0.346		0.362
E	7.20		6.80	0.2.83		0.268

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Revision History

Revision	Changes	Date
1.0	Preliminary Release	6-Nov-2002
1.1	Datasheet updated for Serial and Printer port related details	7-Feb-2005
1.2	Revised Data Sheet	25-Oct-2005
1.3	Minor Layout Changes	17-Nov-2005
1.4	Changes to Serial and Parallel Port Descriptors	28-Nov-2005
1.5	Corrected Polling Intervals	30-Nov-2005
1.6	Corrected Electrical Characteristics and Pin Descriptions	6-Jan-2006